Economic Design of Reinforced Concrete Conical Shells

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Abstract: This work presents economic reinforced concrete conical shells dimensions and reinforcement in order to save time and efforts of the designers who aim to design conical shells economically from 5m to 20m spans. In addition to that, this work presents the economic shell raise (h_{ec}) vs. span (D) formula that gives lowest construction cost.

The considered loads are the own weight of the shell body, external finishing by glazed brick and internal finishing layer of gypsum plaster (juss). As well as the dead load, live load is considered too. A computer program is written in the Visual Basic programming language. This computer program consists of two parts. The first part is the linear analysis using the membrane theory formulas to get the forces at the crown and at the support of the shell.

The second part uses Nelder and Mead's minimization method to minimize the total cost formula (objective function). Three types of constraints confine this minimization regarding to strength, buckling and accuracy of the analysis method. The minimization variables are two; shell rise (h) and shell thickness (t).

The two parts of the computer program are connected together in a force and cost convergence iterative loop in order to get the dimensions and reinforcement ratios that lead to the minimum cost.

Keywords: Economic, Design, Reinforced Concrete, Conical, Shells.

I. Introduction

Shells are back again in Iraq. They are early recognized with specific houses of those who consider them a symbol of Iraqi architecture ^[1], beauty and luxury at the same time.

Nowadays, shells are widely constructed in Baghdad. Shells built with brick, reinforced concrete or steel; separated or overlapped are widely constructed. This is why this work is implemented to answer the question: What are the dimensions and reinforcement ratios that give the economical design of conical shells?

It is known that when the conical shell is shallow, i.e. the rise (h) is small, the support angle with the horizon (υ) decreases, so the horizontal component (Fx) of the thrust force (N_{thrust}) increases, see figure (1). This leads to an increment in the dimensions and reinforcement of the edge ring beam that raises the total cost of the conical shell.

In other hand, when the conical shell is high, i.e. (h) is big, the dome becomes bigger and the shell becomes thicker which also raise the total cost of the conical shell in spite of the nonexistence need to an expensive edge ring beam.

Therefore, there is a specific solution lies between the high shell and the low one, i.e. a balance among the dimensions of the shell in some way that leads to the minimum cost.

II. Some of Previous Studies

According to the amount and variation of shells constructed from 1920 to 1970, this period of time can be considered the golden time of the reinforced concrete shell construction. Later, reinforced concrete shells began to get less attention. Fewer technical research works are published on their design methods and construction techniques, and the amount of signature shells constructed declined noticeably. Ekkehard Ramm and Gerhard Mehlhorn (1991) discussed the analyses of reinforced concrete shells at ultimate loading. After a brief review of the material models used, the authors presented selected examples such as conical shaped cooling towers that experimentally discussed as a free form model shell through discussing various form-finding approaches for the shape of shells free form ^[2]. M.H. Imam (1998) presented a shape optimization study for 4m span umbrella-shaped axisymmetric shell of variable thickness with the self-weight as the dominant load. Constraints on the principal stresses at the critical points are taken into consideration as design criterion and the assessment of the uniaxial strength (compressive one) requirement is used as failure criterion ^[3]. M Z Kabir and A Rojhani Shirazi (2008) studied the optimum minimum weight laminate configuration for lament-wound laminated conical shells under buckling load. Based on the characteristic buckling behavior takes place in laminated conical shells, the common penalty function technique is used to solve the optimization problem in addition to reduce the computational cost related to it ^[4]. Antonio Tomás and Pascual Martí (2010) presented an aesthetic appearance like initially planned by the designer. The results show that important improvements in the structural behaviour may be reached with only small geometric changes. They showed how increasing the

geometric curvatures, taking a higher elastic modulus of the concrete into considerations and increasing the thickness of shell affect the optimum solution ^[5]. Milaji \Box Aleksandar et al (2013) tried to reduce the gap between practice and theory in the field of optimum design of the RC structures by highlighting the importance of evaluating the obtained solutions from the practical side. In addition to that, Authors provided a brief overview of existing solutions up to 2013 in order to enable researchers to find the adequate comparison criteria and benchmark problems for their solutions of the optimization problem ^[6].

III. **Objective Function**

The objective function of the research, which should be minimized, is the cost function. Cost function includes the costs of concrete volume of the shell body, concrete volume of the edge ring beam and the reinforcement for both involving labor cost. This cost also includes the external and internal finishing of the shell body in addition to the labor cost:

$$Z = Z_{s} + Z_{B} + Z_{th} + Z_{h} + Z_{mB} + Z_{sB}$$
(1)

Where:

Ζ	=	total cost of the shell			
Zs	=	cost of the concrete shell body			
Z _B	=	cost of the concrete ring beam			
Z _{th}	=	cost of the thrust steel reinforcement for the shell body			
Z _h	=	cost of the hoop steel reinforcement for the shell body			
Z _{mB}	=	cost of the main steel reinforcement for the ring beam			
Z _{sB}	=	cost of the shear steel reinforcement for the ring beam			
Equation (1) could be written in more detailed form:					

$$Z = Vol_{sh}*Cc+Vol_{B}*Cc+Vol_{sth}*\gamma_{s}*Cs+Vol_{sho}*\gamma_{s}*Cs+Vol_{stB}*\gamma_{s}$$
$$*Cs+A_{int}*C_{fint}+A_{ext}*C_{fext} + 4 a*no*C_{st}$$

Where:

Vol _{sh}	=	concrete volume of the shell body
Vol _B	=	concrete volume of the edge ring beam
Vol _{sth}	=	volume of meridional steel reinforcement of the shell
Vol _{sho}	=	volume of hoop steel reinforcement of the shell
Vol _{stB}	=	volume of main reinforcement of the ring beam
A _{int}	=	internal surface area of the shell
A _{ext}	=	external surface area of the shell
Cc	=	concrete unit price (unit/m ³) including labor cost
Cs	=	reinforcement steel unit price (unit/ton) including labor cost
C _{fint}	=	juss unit price (unit/m ²) including labor cost
C _{fext}	=	glazed tiles unit price (unit/m ²) including labor cost
C _{st}	=	stirrup unit price including labor cost (unit/stirrup)
γ_{s}	=	reinforcement steel density (ton/m ³)
a	=	dimension of the square ring beam
no	=	number of ring beam stirrups reinforcement

It is worth to mention that Vol_{sh} , Vol_B , A_{int} and A_{ext} are calculated as follow: $Vol_{sh} = \pi . 0.5 D . S . t$ $Vol_B = a^2$. π . D $A_{int}\,\approx\,A_{ext}\,{=}\,0.5~D$. S . π

Where

vv nere.		
D	=	shell span
S	=	shell slant
t	=	shell thickness

IV. Minimization Technique Nelder and Mead's method^[7] is used to minimize the objective function mentioned earlier. The idea of this method is to compare the values of the cost function at (number of variables + 1) vertices of the simplex and

move the simplex towards the minimum point during the iterative process. This search for the minimum Z value is conditioned by specific limitations.

V. Design Variables

The minimization process, which is applied on the objective function, is through varying the values of the design variables in a way that gives the minimum value of (Z). Rise (h) and thickness (t) of the shell are independent design variables, while the other design variables such as reinforcement ratios for shell (ρ_{slab}) and beam (ρ_{beam}), beam stirrups (strps) and ring beam dimension (a) depend on the values of (h) and (t) obtained from minimization process.

VI. Minimization Constraints

In order to get the minimum cost for the conical shell, Z function should be minimized, but minimization is limited by the requirements of strength requirements, buckling considerations and adequacy of membrane theory use:

VI.I Strength requirements:

a) Hoop stress in concrete (σ_H) should not exceed the allowable limit:

 $\sigma_{
m H}$ [$f_{
m t}$

 $\begin{array}{ll} \frac{N_{hoop}}{t} \leq f_t & (2) \\ \text{Where} \\ f_t & = & \text{Allowable tensile strength for concrete} \\ t & = & \text{Shell thickness} \\ N_{hoop} & = & \text{Hoop unit forces} \end{array}$

b) Thrust stress in concrete (σ_{TH}) should not exceed the allowable compressive strength for the concrete: $\sigma_{TH} [f'_c]$

$$\frac{N_{thrust}}{t} \le f_c' \tag{3}$$

Where

 $N_{thrust}' = Allowable compressive strength for concrete N_{thrust} = Meridional unit forces$

VI.II Buckling Considerations:

Calculations for stability in thin conical shells in a nonlinear formulation can be found in the literature ^[8]. The author derived and simplified the differential equation for conical shells, and on that basis, derived theoretical formulas for determining buckling load and buckling stress in axial compression: $\sigma_T [\sigma_{cr}]$

$$\frac{N_{thrust}}{t} \le \sigma_{cr} \tag{4}$$

Buckling allowable stress (σ_{cr}) can be defined by the following formula^[8]:

 $\sigma_{cr} = \frac{0.195 E.t}{r}$ Where: E = elastic modulus r = principal radius of curvature at the point studied for stability

VI.III Membrane Theory Adequacy:

In order to ensure the accuracy of the elastic analysis made by the membrane theory, it should be guaranteed that the ratio of shell thickness (t) to the shell radius of curvature (r) should be within the range identified below $^{[9\&10]}$:

$$\frac{1}{200} \le \frac{t}{r} \le \frac{1}{25} \tag{5}$$

VII. **Design Example**

In order to clarify the membrane theory analysis and design details, a design example of a conical roof covers a hall having a diameter of 20m is presented here. The rise of the conical dome has to be 4m. Live load (LL) is considered 1500 N/ m^2 , see figure (1).





1- Geometry of the shell:

Diameter D = 20 m

rise h = 4 m $\tan v = 10/4 = 2.5$; then $v = 68^{\circ} 12^{\prime}$ $\sin \upsilon = 0.9285$; $\cos \upsilon = 0.3714$

2- Loading:

Let the thickness of the shell be 15cm Weight of dome shell $/m^2 = 0.15 * 1 * 23000 + (0.02+0.04) * 1 * 20000 = 4650 N$ $W_{\mu} = 1.2 (4650) + 1.6 (1500) = 7980 \text{ N/m}^2$

3- Calculation of stresses:

 $N_{thrust} = \frac{W_u \cdot h}{2\cos^2 \theta}$ Thrust Maximum N_{thrust} will occur at the base where h = 4 m $N_{thrust_{max}} = \frac{7980(4)}{2(0.3714)^2} = 115704.2 N$ (comp.) Thrust stresses : $\frac{115704.2}{150(1000)} = 0.771 \, N \, / \, mm^2 \, (Safe)$ Hoop force: $N_{hoop} = W_u \cdot h \cdot tan^2 v$ $N_{\text{hoop})\text{max}} = 7980 (4) (2.5)^2 = 199500 \text{ N} (comp.)$ Hoop stresses : $\frac{199500}{150(1000)} = 1.33 \ N/mm^2 \ (Safe)$

4- Steel reinforcement based on ACI 318-11^[11]:

The stresses work out to be safe. Hence only nominal reinforcement has to be provided 0.18% of the area of concrete.

 $As_{\min} = 0.0018(150)1000 = 270 \, mm^2$ Using 12mm ϕ bars, $A_b = 113 \text{ mm}^2$

DOI: 10.9790/1684-1304078995

 $Spacing = \frac{1000(A_b)}{As_{\min}} = \frac{1000(113)}{270} = 418 \ mm$

Maximum Spacing is 2t = 2(150 mm) = 300 mmUse $12 \text{ mm} \phi$ bars @ 300 mm c/c both directions The meridional bars may be disconnected near apex, and a wire mesh may be provided there to avoid congestion of steel.

5- Design of ring beam:

Horizontal component (Fx) of meridional thrust N_{thrust} will cause an outward force on the support, causing hoop tension. Hence, a ring beam is necessary.

Hoop tension P in ring beam: N_{thrust} sinv = 115704.2 (0.9285) = 107431.35 N/m Total tensile force: P(0.5 D) =107431.35 (0.5) 20 = 1074313.5 N Area of steel to resist this: $As = \frac{1074313.5}{140} = 7673.3 \ mm^2$ Using 25mm ϕ bars, A_b = 490 mm² No. of bars = $\frac{7673.7}{490} \approx 16$ bars Actual area of steel provided = 7840 mm^2 Tie these by 12mm \u03c6 2-lgs stirrups @ 300mm c/c Let (a^2) be the area of ring beam, equivalent area of composite section = $(a^2) + (m-1) As = (a^2) + 18(7840) = (a^2) + 141120$ Assuming the allowable tensile stress in composite section to be 1.2 N/mm², we have: 1074313.5 $\frac{10.13.5}{(a^2) + 141120} = 1.2$ Which gives $a^2 = 754141.25 \text{ mm}^2$ Provide ring beam of size 875mm x 875mm 7840 $\rho = \frac{7840}{(875)(800)} = 0.0112$ $\rho_{\max} = 0.85(0.85) \frac{25}{400} \frac{0.003}{0.003 + 0.004} = 0.01935 > \rho \quad o.k.$

The details of the reinforcement are shown in figure (2).



Figure (2): Design details

VIII. Computer Program

This computer program, see figure (3), is written in the Visual Basic programming language. This computer program consists of two parts. The first part is the linear analysis using the membrane theory formulas to get the forces at the crown and at the support of the shell.

Running this program starts with feeding the values of shell span (D), dome rise (h), concrete compressive strength (f'_c), allowable tensile strength for concrete (f_t), yield of steel stress (fy), density of concrete (γ_c), density of steel (γ_s) and shell thickness (t).

According to the values of span (D), shell thickness (t), and shell rise (h), the linear analysis takes place by the program on the base of the membrane theory closed form solution. The program calculates the forces (N_{hoop}) and (N_{thrust}) at the support and at the crown of the conical shell. After that, the program calculates the hoop stresses (σ_H) and thrust (σ_{TH}) by dividing the calculated forces by the thickness (t). Then, the program checks the stresses with the allowance of crushing and buckling.

At the following step, the program calculates the required reinforcement steel areas in both directions (As_{hoop}) and (As_{thrust}) at the support and the crown of the shell. After that, the program indicates the dimensions and the required steel reinforcement for the ring beam.

The second part of the program uses Nelder and Mead's minimization method to minimize the total cost formula (objective function). Three types of constrains confine this minimization. The minimization variables are two; rise (h) and thickness (t).

Force and cost convergence iterative loops are connecting the two program parts to reach the minimum cost.

The output of the program is shell span (D), economic rise (h_{ec}), shell slab thickness (t), slab reinforcement details, ring beam dimension (a), ring beam reinforcement and total cost (Z).

IX. Results and Conclusions

Using the written design computer program, the economic design dimensions and reinforcement for 5m - 20m conical shells are given in the following table:

Economic Design Dimensions, Reinforcement and Cost

Span	Rise	Thick-	Reinforce-	Reinf.	Beam	Reinforce-	Reinf.	Stir-	Total
(m)	(m)	ness	ment	ratio	Dimen-	ment	ratio	rups	Cost
D	h	(mm)	for slab	ρ_{slab}	sions	for beam	ρ_{beam}	for Beam	(unit)
			(both ways)		(m)				
5	0.625	75	Ø8@	0.0018	0.2 * 0.2	4 - ø12	0.01130	Ø6@	634
			350mm					300mm	
10	2.5	100	Ø10mm	0.0018	0.3 * 0.3	8 – Ø12mm	0.010053	Ø8mm@	3476
			@425mm					300mm	
15	4.1	125	Ø12@450mm	0.0018	0.5 * 0.5	12 - Ø16	0.00965	Ø10@300	12609
								mm	
20	6.9	150	Ø16@450mm	0.0018	0.6 * 0.6	8 - Ø25	0.01090	Ø12@300	30700
								mm	

Economical dimensions can be summarized by figure (3):





The curve of the economic rise (h_{ec}) vs span of the conical shells from 5m to 20m spans can be expressed by the following formula:

$$h_{ec} = \frac{D^3}{508.4746} - 0.0645D^2 + 0.99833 D - 3$$
(6)

$$\int try t data D, LL, f, f, f, f, y, y, and y, try t data D, LL, f, f, f, f, f, y, y, and y, try t data D, LL, f, f, f, f, y, y, and y, try t data D, LL, f, f, f, f, f, y, y, and y, try t data D, LL, f, f, f, f, f, y, y, and y, try t data D, LL, f, f, f, f, f, y, y, and y, try t data D, h, try t data D, h,$$

Figure (3): Program Structure

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