

Derivation and Application of Six-Point Linear Multistep Numerical Method for Solution of Second Order Initial Value Problems

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Abstract: A six-step Continuous Block method of order $(5, 5, 5, 5, 5, 5)^T$ is proposed for direct solution of the second (2nd) order initial value problems. The main method and additional ones are obtained from the same continuous interpolant derived through interpolation and collocation procedures. The methods are derived by interpolating the continuous interpolant at $x = x_{n+j}$, $j = 6$ and collocating the first and second derivative of the continuous interpolant at x_{n+j} , $j = 0$ and $j = 2, 3, \dots, 5$ respectively. The stability properties of the methods are discussed and the stability region shown. The methods are then applied in block form as simultaneous numerical integrators. Two numerical experiments are given to illustrate the efficiency of the new methods.

Keywords: Collocation and Interpolation, Second Order Equations, Block Method, Initial Value Problem.

I. Introduction

In this paper, efforts are directed towards constructing a uniform order 5 block methods for solution of general second order ordinary differential equation of the form.

$$y'' = f(x, y, y'), \quad y(0) = \alpha_1, \quad y'(0) = \beta \quad (1)$$

In the past, efforts have been made by eminent scholars to solve higher order initial value problems especially the second order ordinary differential equation. In practice, this class of problem (1) is usually reduced to system of first order differential equation and numerical methods for first order Odes then employ to solve them, Fatunla (1988) and Lambert (1973). Awoyemi (1999) showed that reduction of higher order equations to its first order has a serious implication in the results; hence it is necessary to modify existing algorithms to handle directly this class of problem (1). Yahaya and Badmus (2009) demonstrated a successful application of LMM methods to solve directly a general second order odes of the form (1) though with non-uniform order member block method, this idea is used and now extended to our own uniform order block schemes to solve the type (1) directly.

We approximate the exact solution $y(x)$ by seeking the continuous method $\bar{y}(x)$ of the form

$$\bar{y}(x) = \sum_{j=0}^{s+r-1} \alpha_j(x) y_{n+j} + h^2 \sum_{j=0}^{r-1} \beta_j(x) f_{n+j} \quad (2)$$

Where $x \in [a, b]$ and the following notations are introduced. The positive integer $k \geq 2$ denotes the step number of the method (2), which is applied directly to provide the solution to (1).

II. Derivation Of The New Block Methods

We propose an approximate solution to (1) in the form:

$$y_k(x) = \sum_{j=0}^{s+r-1} V_j x^j \quad (3)$$

$$y'_k(x) = \sum_{j=0}^{s+r-1} j V_j x^{(j-1)} \quad (4)$$

$$y''_k(x) = \sum_{j=0}^{s+r-1} j(j-1) V_j x^{(j-2)} = f(x, y, y') \quad (5)$$

Now, interpolating (3) at x_{n+j} , $j = 6$ and collocating (5) at x_{n+j} , $j = 2, 3, \dots, 5$ leads to a system of equations written in the form.

$$\begin{aligned} V_0 + V_1 x_n + V_2 x_n^2 + V_3 x_n^3 + V_4 x_n^4 + V_5 x_n^5 + V_6 x_n^6 &= y_n \\ V_0 + V_1 x_{n+1} + V_2 x_{n+1}^2 + V_3 x_{n+1}^3 + V_4 x_{n+1}^4 + V_5 x_{n+1}^5 + V_6 x_{n+1}^6 &= y_{n+1} \\ V_0 + V_1 x_{n+2} + V_2 x_{n+2}^2 + V_3 x_{n+2}^3 + V_4 x_{n+2}^4 + V_5 x_{n+2}^5 + V_6 x_{n+2}^6 &= y_{n+2} \\ V_0 + V_1 x_{n+3} + V_2 x_{n+3}^2 + V_3 x_{n+3}^3 + V_4 x_{n+3}^4 + V_5 x_{n+3}^5 + V_6 x_{n+3}^6 &= y_{n+3} \\ V_0 + V_1 x_{n+4} + V_2 x_{n+4}^2 + V_3 x_{n+4}^3 + V_4 x_{n+4}^4 + V_5 x_{n+4}^5 + V_6 x_{n+4}^6 &= y_{n+4} \\ V_0 + V_1 x_{n+5} + V_2 x_{n+5}^2 + V_3 x_{n+5}^3 + V_4 x_{n+5}^4 + V_5 x_{n+5}^5 + V_6 x_{n+5}^6 &= y_{n+5} \\ 2V_2 + 6V_3 x_{n+6} + 12V_4 x_{n+6}^2 + 20V_5 x_{n+6}^3 + 30V_6 x_{n+6}^4 &= f_{n+6} \end{aligned} \quad (6)$$

Where V_j 's are the parameters to be determined.

When re-arranging (6) in a matrix form $AX = B$, we obtained

$$\begin{pmatrix} 1 & x_n & x_n^2 & x_n^3 & x_n^4 & x_n^5 & x_n^6 \\ 1 & x_{n+1} & x_{n+1}^2 & x_{n+1}^3 & x_{n+1}^4 & x_{n+1}^5 & x_{n+1}^6 \\ 1 & x_{n+2} & x_{n+2}^2 & x_{n+2}^3 & x_{n+2}^4 & x_{n+2}^5 & x_{n+2}^6 \\ 1 & x_{n+3} & x_{n+3}^2 & x_{n+3}^3 & x_{n+3}^4 & x_{n+3}^5 & x_{n+3}^6 \\ 1 & x_{n+4} & x_{n+4}^2 & x_{n+4}^3 & x_{n+4}^4 & x_{n+4}^5 & x_{n+4}^6 \\ 1 & x_{n+5} & x_{n+5}^2 & x_{n+5}^3 & x_{n+5}^4 & x_{n+5}^5 & x_{n+5}^6 \\ 0 & 0 & 2 & 6x_{n+5} & 12x_{n+5}^2 & 20x_{n+5}^3 & 30x_{n+5}^4 \end{pmatrix} \begin{pmatrix} V_0 \\ V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \\ V_6 \end{pmatrix} = \begin{pmatrix} y_n \\ y_{n+1} \\ y_{n+2} \\ y_{n+3} \\ y_{n+4} \\ y_{n+5} \\ f_{n+6} \end{pmatrix}$$

$$\begin{aligned} y(x) = & q := \left(\frac{-58997}{24360} \frac{x}{h} + \frac{58997}{24360} \frac{x_n}{h} + \frac{14235}{6496} \frac{\xi^2}{h^2} - \frac{37733}{38976} \frac{\xi^3}{h^3} \right. \\ & \left. + \frac{2899}{12992} \frac{\xi^4}{h^4} - \frac{4999}{194880} \frac{\xi^5}{h^5} + 1 + \frac{15}{12992} \frac{\xi^6}{h^6} \right) y_n \\ & + \left(\frac{2355}{406} \frac{x}{h} - \frac{2355}{406} \frac{x_n}{h} - \frac{11209}{9744} \frac{\xi^4}{h^4} + \frac{43451}{9744} \frac{\xi^3}{h^3} \right. \\ & \left. - \frac{13389}{1624} \frac{\xi^2}{h^2} - \frac{65}{9744} \frac{\xi^6}{h^6} + \frac{1381}{9744} \frac{\xi^5}{h^5} \right) y_{n+1} \\ & + \left(\frac{-5595}{812} \frac{x}{h} + \frac{5595}{812} \frac{x_n}{h} + \frac{307}{19488} \frac{\xi^6}{h^6} + \frac{42981}{3248} \frac{\xi^2}{h^2} \right. \\ & \left. - \frac{164891}{19488} \frac{\xi^3}{h^3} + \frac{47207}{19488} \frac{\xi^4}{h^4} - \frac{6229}{19488} \frac{\xi^5}{h^5} \right) y_{n+2} + \left(\right. \\ & \left. - \frac{9525}{812} \frac{\xi^2}{h^2} + \frac{3425}{609} \frac{x}{h} - \frac{3425}{609} \frac{x_n}{h} - \frac{4259}{1624} \frac{\xi^4}{h^4} \right. \\ & \left. + \frac{40819}{4872} \frac{\xi^3}{h^3} - \frac{31}{1624} \frac{\xi^6}{h^6} + \frac{1801}{4872} \frac{\xi^5}{h^5} \right) y_{n+3} \\ & + \left(\frac{37563}{6496} \frac{\xi^2}{h^2} - \frac{170309}{38976} \frac{\xi^3}{h^3} + \frac{-4335}{1624} \frac{x}{h} + \frac{4335}{1624} \frac{x_n}{h} \right. \\ & \left. - \frac{8539}{38976} \frac{\xi^5}{h^5} + \frac{57049}{38976} \frac{\xi^4}{h^4} + \frac{461}{38976} \frac{\xi^6}{h^6} \right) y_{n+4} + \left(\right. \\ & \left. - \frac{69}{56} \frac{\xi^2}{h^2} + \frac{39}{70} \frac{x}{h} - \frac{39}{70} \frac{x_n}{h} + \frac{323}{336} \frac{\xi^3}{h^3} - \frac{113}{336} \frac{\xi^4}{h^4} \right. \\ & \left. - \frac{1}{336} \frac{\xi^6}{h^6} + \frac{89}{1680} \frac{\xi^5}{h^5} \right) y_{n+5} + \left(\left(-\frac{15}{406} \frac{x}{h} + \frac{15}{406} \frac{x_n}{h} \right) h \right. \\ & \left. + \frac{85}{3248} \frac{\xi^4}{h^2} - \frac{15}{3248} \frac{\xi^5}{h^3} + \frac{1}{3248} \frac{\xi^6}{h^4} - \frac{225}{3248} \frac{\xi^3}{h} \right. \\ & \left. + \frac{137}{1624} \xi^2 \right) f_{n+6} \end{aligned}$$

(7)

Where V_j 's are obtained as continuous coefficients of $\alpha_j(x)$ and $\beta_j(x)$
Specifically, from (2) the proposed solution takes the form

$$y(x) = \alpha_0(x) y_n + \alpha_1(x) y_{n+1} + \alpha_2(x) y_{n+2} + \alpha_3(x) y_{n+3} + \alpha_4(x) y_{n+4} + \alpha_5(x) y_{n+5} + h^2 [\beta_6(x) f_{n+6}] \tag{8}$$

A mathematical software (maple) is used to obtain the inverse of the matrix in equation (7) where values for V_j 's were established. After some manipulation to the inverse, we obtained the continuous interpolant of the form:

(9)

Evaluating (9) at x_{n+j} , $j = 6$ and its second derivative evaluated at x_{n+j} , $j = 2, \dots, 5$ while its 1st derivative is evaluated at x_{n+j} , $j = 0$ yields the following set of discrete equations.

$$\begin{aligned} & \frac{29}{45} y_{n+6} - \frac{783}{315} y_{n+5} + \frac{1053}{252} y_{n+4} - \frac{254}{63} y_{n+3} + \frac{1485}{630} y_{n+2} - \frac{243}{315} y_{n+1} + \frac{137}{1260} y_n = \frac{h^2}{7} [f_{n+6}] \\ & \frac{5162}{3} y_{n+5} - \frac{61891}{12} y_{n+4} + \frac{17960}{3} y_{n+3} - \frac{21277}{6} y_{n+2} + \frac{3478}{3} y_{n+1} - \frac{1955}{12} y_n = h^2 [812f_{n+5} - 137f_{n+6}] \\ & 2407y_{n+5} - \frac{18173}{4} y_{n+4} + 1606y_{n+3} + \frac{1693}{2} y_{n+2} - 373y_{n+1} + \frac{227}{4} y_n = h^2 [39f_{n+6} + 2436f_{n+4}] \\ & \frac{87}{2} y_{n+5} - \frac{2319}{3} y_{n+4} + 1077y_{n+3} - \frac{1185}{2} y_{n+2} + \frac{111}{2} y_{n+1} - \frac{15}{4} y_n = h^2 [f_{n+6} - 406f_{n+3}] \\ & \frac{29}{3} y_{n+5} - \frac{55}{12} y_{n+4} - \frac{1438}{3} y_{n+3} + \frac{5783}{6} y_{n+2} - \frac{1559}{3} y_{n+1} + \frac{361}{12} y_n = h^2 [f_{n+6} - 406f_{n+2}] \\ & \frac{377}{25} y_{n+5} - \frac{289}{4} y_{n+4} + \frac{5480}{36} y_{n+3} - \frac{373}{2} y_{n+2} + 157y_{n+1} - \frac{58997}{900} y_n - \frac{406}{15} hZ_n = h^2 f_{n+6} \end{aligned} \tag{10}$$

Where $Z_n = y_n'$

Equation (10) is the proposed six-step block method. The application of the block integrators (10) with $n = 0$, give the values of y_1, y_2, y_3, y_4, y_5 and y_6 directly without the use of starting values.

III. Analysis of the Method

Order and error constant

Following Fatunla [5, 6 and 7] and Lambert [9 and 10] we define the local truncation error associated with the conventional form of (2) to be the linear difference operator.

$$L[y(x); h] = \sum_{j=0}^k \alpha_j y(x + jh) - h^2 \beta_j y''(x + jh) \tag{11}$$

Where the constant coefficients $C_q, q = 0, 1 \dots$ are given as follows:

$$C_q = \sum_{j=0}^k \alpha_j$$

$$C_1 = \sum_{j=0}^k j \alpha_j$$

.

.

$$C_q = \frac{1}{q!} \sum_{j=0}^k j^q \alpha_j - q(q-1) \sum_{j=0}^k j^{q-2} \beta_j \tag{12}$$

According to Henrici [10], we say that the method (2) has order P if

$$C_0 = C_1 = C_2 = \dots = C_p = C_{p+1} = 0, \quad C_{p+2} \neq 0$$

Our calculations reveal that the Block methods (10) have uniform order P=5 and error constant given by the vector

$$C_7 = \left(-\frac{1}{10}, \frac{13077}{90}, -\frac{1631}{30}, -\frac{7}{10}, -\frac{469}{10}, -\frac{137}{30} \right)^T$$

IV. Convergence

The block methods shown in (10) can be represented by a matrix finite difference equation in the form:

$$IY_{w+1} = AY_{w-1} + h^2 [\beta_1 F_{w+1} + \beta_0 F_{w-1}] \tag{13}$$

Where

$$\begin{aligned} Y_{w+1} &= (y_{n+1}, \dots, y_{n+6})^T, & Y_{w-1} &= (y_{n-5}, \dots, y_n)^T, \\ F_{w+1} &= (F_{n+1}, \dots, F_{n+6})^T, & F_{w-1} &= (F_{n-4}, \dots, F_n)^T, \end{aligned}$$

And $w = 0, 1, 2, \dots$ and n is the grid index

$$I = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$B_1 = \begin{pmatrix} 0 & \frac{2641}{480} & -\frac{4991}{360} & \frac{2849}{240} & -\frac{959}{120} & \frac{475}{288} \\ 0 & \frac{33}{2} & -\frac{1772}{45} & \frac{827}{15} & -\frac{332}{15} & \frac{409}{90} \\ 0 & \frac{4599}{180} & -\frac{525}{8} & \frac{5642}{80} & -\frac{1487}{40} & \frac{1203}{180} \\ 0 & \frac{818}{15} & -\frac{4098}{45} & \frac{298}{3} & -\frac{258}{5} & \frac{472}{45} \\ 0 & \frac{5125}{96} & -\frac{8275}{72} & \frac{8125}{48} & -\frac{525}{8} & \frac{2875}{288} \\ 0 & \frac{657}{10} & -\frac{708}{5} & \frac{782}{5} & -\frac{298}{5} & \frac{33}{2} \end{pmatrix}$$

And

$$-\frac{708}{5} \quad \frac{783}{5} \quad -\frac{396}{5} \quad \frac{33}{2}$$

and $B_0 = 0$

It is worth noting that zero-stability is concerned with the stability of the difference system in the limit as h tends to zero. Thus, as $h \rightarrow 0$, the method (13) tends to the difference system.

$$IY_{w+1} - AY_{w-1} = 0$$

Whose first characteristic polynomial $\rho(Q)$ is given by

$$\rho(Q) = \det(QI - A)$$

$$= Q^5(Q - 1) \tag{14}$$

Following Fatunla [7], the block method (13) is zero-stable, since from (14), $\rho(Q) = 0$ satisfy $|Q_j| \leq 1, j = 1, \dots, k$ and for those roots with $|Q_j| = 1$, the multiplicity does not exceed 2. The block method (13) is consistent as it has order $P > 1$. Accordingly following Henrici [8], we assert the convergence of the block method (13).

V. Stability Region Of The Block Method

To compute and plot absolute stability region of the block methods, the block method is reformulated as General Linear Methods expressed as:

$$\begin{pmatrix} Y \\ y_{n+1} \end{pmatrix} = \begin{pmatrix} A & U \\ B & V \end{pmatrix} \begin{pmatrix} hf(y) \\ y_{i-1} \end{pmatrix}$$

Where

$$A = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & \frac{900}{141300} \\ 0 & 0 & -\frac{4872}{11580} & 0 & 0 & 0 & \frac{32}{11580} \\ 0 & 0 & 0 & -\frac{1824}{4208} & 0 & 0 & \frac{4}{4208} \\ 0 & 0 & 0 & 0 & -\frac{9744}{18172} & 0 & -\frac{156}{18172} \\ 0 & 0 & 0 & 0 & \frac{9744}{20648} & -\frac{1844}{20648} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & \frac{45}{202} \end{pmatrix}$$

$$B = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & \frac{45}{202} \\ 0 & 0 & 0 & 0 & 0 & \frac{9744}{20848} & -\frac{1844}{20848} \\ 0 & 0 & 0 & 0 & -\frac{9744}{18172} & 0 & -\frac{158}{18172} \\ 0 & 0 & 0 & -\frac{1824}{4208} & 0 & 0 & \frac{4}{4208} \\ 0 & 0 & -\frac{4872}{11568} & 0 & 0 & 0 & \frac{12}{11568} \\ 0 & 0 & 0 & 0 & 0 & 0 & \frac{900}{141200} \end{pmatrix}$$

$$U = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 \\ -\frac{12572}{141200} & \frac{85025}{141200} & -\frac{127000}{141200} & \frac{187850}{141200} & 0 & \frac{58997}{141200} \\ -\frac{118}{11568} & \frac{55}{11568} & \frac{5752}{11568} & 0 & \frac{8228}{11568} & -\frac{281}{11568} \\ \frac{174}{4208} & \frac{2319}{4208} & 0 & \frac{2370}{4208} & -\frac{222}{4208} & \frac{15}{4208} \\ \frac{9828}{18172} & 0 & \frac{8424}{18172} & \frac{2288}{18172} & -\frac{1492}{18172} & \frac{227}{18172} \\ 0 & \frac{81891}{20848} & -\frac{71840}{20848} & \frac{42554}{20848} & -\frac{12912}{20848} & \frac{1955}{20848} \\ \frac{27}{7} & -\frac{5285}{812} & \frac{1270}{202} & -\frac{1485}{408} & \frac{243}{202} & -\frac{127}{812} \end{pmatrix}$$

$$V = \begin{pmatrix} \frac{27}{7} & -\frac{5285}{812} & \frac{1270}{202} & -\frac{1485}{408} & \frac{243}{202} & -\frac{127}{812} \\ 0 & \frac{81891}{20848} & -\frac{71840}{20848} & \frac{42554}{20848} & -\frac{12912}{20848} & \frac{1955}{20848} \\ \frac{9828}{18172} & 0 & \frac{8424}{18172} & \frac{2288}{18172} & -\frac{1492}{18172} & \frac{227}{18172} \\ -\frac{174}{4208} & \frac{2319}{4208} & 0 & \frac{2370}{4208} & -\frac{222}{4208} & \frac{15}{4208} \\ -\frac{118}{11568} & \frac{55}{11568} & \frac{5752}{11568} & 0 & \frac{8228}{11568} & -\frac{281}{11568} \\ -\frac{12572}{141200} & \frac{85025}{141200} & -\frac{127000}{141200} & \frac{187850}{141200} & 0 & \frac{58997}{141200} \end{pmatrix}$$

Substituting the values of A, B, U, V into stability matrix and stability function, then using maple package yield the stability polynomial of the block method. Using a matlab program, we plot the absolute stability region of our proposed block method (see Fig. 1).

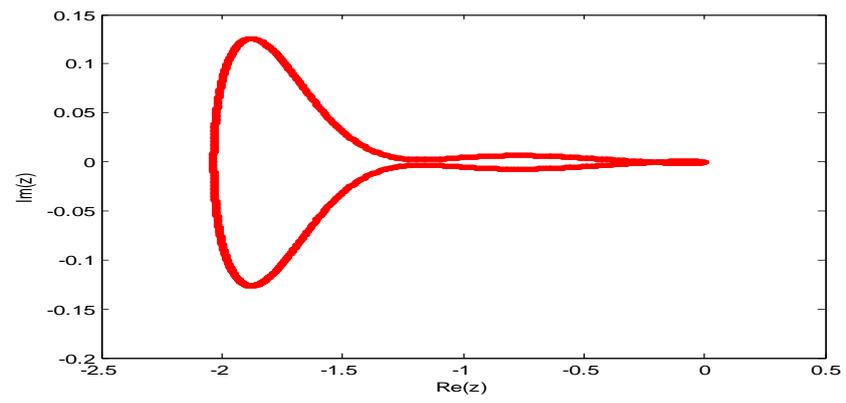


Fig. 1: Region of Absolute Stability

VI. IMPLEMENTATION STRATEGIES

In this section, we have tested the performance of our six-step block method on two (2) numerical problems by considering two IVPs (Initial Value Problems). For each example; we find the absolute errors of the approximate solution.

Example 1.1: We consider the IVP for the step-size $h = 0.01$

$$y'' - 100y = 0, y(0) = 1, y'(0) = -10$$

Table of results and absolute errors for problem 1.1

| x | $y(x)$ | y | Errors |
|------|--------------|--------------|----------|
| 0 | 1.0000000000 | 1.0000000000 | 0.00e+0 |
| 0.01 | 0.9048374180 | 0.9048372827 | 1.353e-7 |
| 0.02 | 0.8187307531 | 0.8187303873 | 3.658e-7 |
| 0.03 | 0.7408182207 | 0.7408176156 | 6.051e-7 |
| 0.04 | 0.6703200460 | 0.6703191958 | 8.502e-7 |
| 0.05 | 0.6065306597 | 0.6065295559 | 1.104e-6 |
| 0.06 | 0.5488116364 | 0.5488102673 | 1.369e-6 |
| 0.07 | 0.4965853038 | 0.4965838539 | 1.450e-6 |
| 0.08 | 0.4493289641 | 0.4493273672 | 1.597e-6 |
| 0.09 | 0.4065696597 | 0.4065678968 | 1.763e-6 |
| 0.10 | 0.3678794412 | 0.3678774948 | 1.946e-6 |
| 0.11 | 0.3328710837 | 0.3328689844 | 2.099e-6 |
| 0.12 | 0.3011942119 | 0.3011918381 | 2.374e-6 |

Absolute Errors $|y(x) - y|$, for example 1.1, where $y(x) = e^{-10x}$

Example 1.2: We consider the IVP for the step-size $h = 0.1$

$$y'' + y = 0, y(0) = 1, y'(0) = 1$$

Table of results and absolute errors for problem 1.2

| X | $y(x)$ | y | Errors |
|-----|--------------|--------------|----------|
| 0 | 1.0000000000 | 1.0000000000 | 0.00e-0 |
| 0.1 | 1.0948375819 | 1.0948374662 | 1.157e-7 |
| 0.2 | 1.1787359086 | 1.1787355987 | 3.099e-7 |
| 0.3 | 1.2508566958 | 1.2508561903 | 5.055e-7 |
| 0.4 | 1.3104793363 | 1.3104786406 | 6.957e-7 |
| 0.5 | 1.3570081005 | 1.3570072216 | 8.789e-7 |
| 0.6 | 1.3899780883 | 1.3899770347 | 1.054e-6 |
| 0.7 | 1.4090598745 | 1.4090588666 | 1.008e-6 |
| 0.8 | 1.4140628003 | 1.4140618777 | 9.226e-7 |
| 0.9 | 1.4049368779 | 1.4049360518 | 8.261e-7 |
| 1.0 | 1.3417732907 | 1.3417725691 | 7.216e-7 |
| 1.1 | 1.3448034815 | 1.3448028716 | 6.099e-7 |
| 1.2 | 1.2943968404 | 1.2943963485 | 4.919e-7 |

Absolute Errors $|y(x) - y|$, for example 1.2, where $y(x) = \text{Cos}x + \text{Sin}x$

VII. Conclusions

We have proposed a six-step block LMM with continuous coefficients from which multiple finite difference methods were obtained and applied as simultaneous numerical integrators, without first adapting the ODE to an equivalent first order system. The method is derived through interpolation and collocation procedures by the matrix inverse approach. We conclude that our new six-step block method of uniform order 5 is suitable for direct solution of general second order differential equations. The new block methods are self-starting and all the discrete schemes used were obtained from the single continuous Formulation and its derivative which are of uniform order of accuracy. The results were obtained in block form which speeds up the computational process and the result obtained from the two numerical examples converges with the theoretical solutions.

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