Generation of Electricity by Using Footsteps as a Source of Energy

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Abstract: Electricity is a basic part of nature and it is one of the most widely used forms of energy across the globe. We get electricity, (which is a secondary energy source) from the conversion of other sources of energy, like coal, natural gas, oil, nuclear power and other natural sources, which are called primary sources. Researches show that the world has already had its enough shares of its energy resources. Fossil fuels pollute the environment. Nuclear energy requires careful handling of both raw as well as waste material. Researches shows that large amount of power is generated from non-renewable energy resources compared to that of renewable energy resources. The extensive usages of available resources in recent years created a demand for the future generation. To overcome this problem we need to utilize renewable energy sources for power generation and conservation. Therefore the focus now is shifting more and more towards the renewable source of energy, which are essential and non-polluting. The goal of this paper is to show the detailed survey of how jumping platform can be now used as a source of power.

Keywords: Renewable energy, rack and pinion, kinetic energy, electro-mechanical unit, roller mechanism, chain sprocket.

I. Introduction

Is anyone happy with the current situation of electricity in India? So, this is our small step to try to improve this situation by our project. First of all what does electricity mean to us??? Electricity- secondary source of energy i.e. converted from other sources. We need it for every small thing, still notice its importance only during load shedding. Man has needed the use energy at an increasing rate for his sustenance and well-being ever since he came on the earth a few million years ago. Primitive man required energy primarily in the form of wood. He derived this by eating plants or animals, which he hunted. Subsequently he discovered force and his energy needs increased as he started to make use of wood and other bio-mass to supply the energy needs for cooking as well as for a keeping himself warm. With the passage of time, man started to cultivate land for agriculture. He added a new dimension to the use of energy by domesticating and training animals to work for him. For this project the conversion of force energy is co
other creative techniques of power generation have been emerged. The newly developed techniques are aimed at cost effectiveness. Thus, they become more affordable to the countries like India, where installation cost and space occupancy are serious issues. One such creative technique is power generation through human powered mechanical energy. The idea is to tap the energy that a human would release while he is jumping. It is achieved by using rack and pinion mechanism. Rack and pinion mechanism, on the contrary, is clean and environmentally friendly, although, the components of the device require regular oiling and maintenance. The initial investment can be recovered within a relatively short time. Jumping is the one of the most common activity in day to day life. One can maintain good health only if he does daily and regular exercise. It is one of the best exercises to maintain body fitness. When a person jumps, he loses energy to the ground surface in the form of impact, vibration, sound etc., due to the transfer of his weight on to the ground surface, through feet falls on the ground during every leap. This energy can be tapped and converted into usable electrical form.In this project, we have used a similar concept to derive electricity using the “jump” energy. The working principle is simple. When a person jumps on the spring cladded platform of the device, the platform will dip down due to the weight of the person. The downward movement of the platform is connected to a specific rack and pinion mechanism, which results in the rotation of the shaft of an electrical generator, to produce electrical energy. The platform reverts back to its original position due to negating springs provided in the device. If such a device is embedded on gymnasium floors or places of human attraction e.g. city malls, amusement parks, etc. the electricity generated by these devices can be used for various day to day applications.

II. Concept

While jumping, the person possess some energy and it is being wasted. This energy can be utilized to produce power by using a special arrangement. It is an Electro-Mechanical unit. It utilizes both mechanical technologies and electrical techniques for the power generation and its storage. Whenever the person is allowed to jump on the base (plywood) it gets pressed downwards then the springs are attached at each corner of the plywood is compressed and the rack which is attached to the plywood moves linearly downward. Since the rack has teeth connected to gears, there exists conversion of linear motion of rack into rotary motion of gears but the two gears rotate in opposite direction. A flywheel is mounted on the shaft whose function is to regulate the fluctuation in the energy and to make the energy uniform. So that the shafts will rotate with certain R.P.M. these shafts are connected through intermediate gears and sprockets to the dynamo, which converts the mechanical energy into electrical energy. The conversion will be proportional to the load being applied. The springs being attached will regain its original length and also cause the plywood to return back to its initial position. This results in the upward motion of the rack which is attached to the plywood thereby rotating the gears. Thus both the downward and upward linear motion of the rack is utilized to generate electricity. Whenever an armature rotates between the magnetic fields of south and north poles, an E.M.F is induced in it. So, for inducing the E.M.F.armature coil has to rotate, for rotating this armature it is connected to a long shaft. By rotating same e.m.f is induced, for this rotation energy of person jumping on the plywood is utilized. This generated power can be amplified and stored by using different electrical devices.

III. Constructional Details

The system comprises of a base (plywood) which rests on a strong platform with four springs in between them. The spring system consists of four springs with a pipe provided to each one to serve as a guide for the springs. The pipe is attached to the rectangular plate which is attached to the plywood. To guide the pipe triangular plates with suitable hole is attached at each corner to the platform as shown in Fig.2. The gearbox consists of a both side toothed rack, two pinions, four intermediate gears, three sprockets and an output gear.
The rack moves linearly between two pinions. The two pinions are connected to two separate sprockets which are constrained to rotate in one direction only (say anti-clockwise). The sprocket is thereby connected to two intermediate gears. When the rack moves linearly downward during the impact of load on the platform, it causes both the pinion to rotate. But the direction of motion is opposite, that is one of the pinions rotates clockwise while the other anti-clockwise. These pinions provide motion to the sprocket but as sprockets are constrained to move in anticlockwise direction, only one of the sprocket rotates during the downward motion of the rack. This rotating rack causes intermediate gear coupled to it to rotate and thereby transfer the motion to another sprocket. This sprocket rotates the gear attached to the flywheel and this gear in turn rotates the output gear. The motion available at the output gear is utilized to run the dynamo to generate electricity. Now, the compressed spring during the downward motion of the base expands to obtain its original length causing the base (plywood) to rise back. During this motion the rack moves upwards and rotates both the pinions in opposite direction. These pinions causes the sprocket to rotate. But only one sprocket will rotate and this time the other one. Thus, both the motion of the rack is utilized that is upward and downward.

Fig. 3. Assembly of gearbox

IV. Experimental Investigation

When a person jumps on the base (plywood) his weight causes an impact on it. This load is distributed uniformly over the plywood. This load causes the springs to compress. The rack which is attached to the base moves linearly downward and rotates the two pinions meshing with it. It is obvious that the pinions will rotate in opposite direction. These pinions while rotating causes the sprocket to rotate. As sprockets are constrained to rotate in one direction, only one of the sprockets will be in motion during a particular rack movement i.e. downward or upward. When the rack moves linearly downward during the impact of load on the platform, it causes both the pinion to rotate. But the direction of motion is opposite, that is one of the pinions rotates clockwise while the other anti-clockwise. These pinions provide motion to the sprocket but as sprockets are constrained to move in anticlockwise direction, only one of the sprocket rotates during the downward motion of the rack. This rotating rack causes intermediate gear coupled to it to rotate and thereby transfer the motion to another sprocket. This sprocket rotates the gear attached to the flywheel and this gear in turn rotates the output gear. The motion available at the output gear is utilized to run the dynamo to generate electricity. Now, the compressed spring during the downward motion of the base expands to obtain its original length causing the base (plywood) to rise back. During this motion the rack moves upwards and rotates both the pinions in opposite direction. These pinions causes the sprocket to rotate. But only one sprocket will rotate and this time the other one. Thus, both the motion of the rack is utilized that is upward and downward. The motion at the output gear causes the dynamo to generate electricity.
A flywheel is also provided to compensate for the reduction in motion. The primary function of flywheel is to act as an energy accumulator. It reduces the fluctuations in speed. It absorbs the energy when demand is less and releases the same when it is required.

Table 1: Power developed at various loads

<table>
<thead>
<tr>
<th>Sr. No.</th>
<th>Load (kg)</th>
<th>Power (W)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>50</td>
<td>0.82</td>
</tr>
<tr>
<td>2</td>
<td>55</td>
<td>0.9</td>
</tr>
<tr>
<td>3</td>
<td>60</td>
<td>0.98</td>
</tr>
<tr>
<td>4</td>
<td>65</td>
<td>1.06</td>
</tr>
<tr>
<td>5</td>
<td>70</td>
<td>1.14</td>
</tr>
<tr>
<td>6</td>
<td>80</td>
<td>1.31</td>
</tr>
</tbody>
</table>

Table 2: Results

<table>
<thead>
<tr>
<th>Sr. No.</th>
<th>Mass (kg)</th>
<th>Voltage (V)</th>
<th>Resistance (Ω)</th>
<th>Current (A)</th>
<th>Power(watt)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>50</td>
<td>2.5</td>
<td>50</td>
<td>0.05</td>
<td>0.125</td>
</tr>
<tr>
<td>2</td>
<td>55</td>
<td>2.94</td>
<td>50</td>
<td>0.0588</td>
<td>0.173</td>
</tr>
<tr>
<td>3</td>
<td>60</td>
<td>3.5</td>
<td>50</td>
<td>0.07</td>
<td>0.245</td>
</tr>
<tr>
<td>4</td>
<td>65</td>
<td>4</td>
<td>50</td>
<td>0.08</td>
<td>0.32</td>
</tr>
<tr>
<td>5</td>
<td>70</td>
<td>4.3</td>
<td>50</td>
<td>0.086</td>
<td>0.3698</td>
</tr>
<tr>
<td>6</td>
<td>80</td>
<td>5.2</td>
<td>50</td>
<td>0.104</td>
<td>0.5408</td>
</tr>
</tbody>
</table>

V. Efficiency

Since, the power is obtained by jumping on the base it can be considered as an input and the power obtained from the dynamo is output. These two quantities are sufficient to calculate the efficiency of the model (setup).

Average theoretical power = \((0.82 + 0.9 + 0.98 + 1.06 + 1.14 + 1.31)/6\) = 1.035 W

Average actual power = \((0.125 + 0.173 + 0.245 + 0.32 + 0.3698 + 0.5408)/6\) = 0.2956 W

Efficiency = Output/ Input = 0.2856 or 28.56%

5.2 Graphs

Graphs of power vs. load, current vs. load and voltage vs. load are plotted below
- It can be seen from the above plotted graph 5 that as load increases power increases.
- The curve is linear.
- It is observed from the above plotted graph 6 that as load increases power increases.
- It is observed from the above plotted graph 7 that as load increases current increases.
It is observed from the above plotted graph 7 that as load increases voltage increases.
It can be observed from the above graph 8 that
• both theoretical and actual power increases with increase in load
• actual power is lower than the theoretical power.
VI. Conclusion

1. It is concluded that
   - as load increases on the base (plywood) voltage increases
   - as load increases on the base (plywood) current increases
   - as load increases on the base (plywood) power increases
   - the efficiency of the setup is found to be 28.56%.
2. The average actual power obtained is 0.2956 W.
   Therefore, power developed per minute = 0.2956 x 60 = 17.74 W
3. If a person jumps for 10 minutes on the base of the setup,
   Power developed in 10 minutes = 177.4 W

References


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