

Fuzzy Logic based Maximum Power Point Tracker for a PV System

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Abstract : In this age of depleting fossil fuels, more emphasis has to be placed on the renewable sources of energy. People are conscious about a clean and pollution free environment and thus a primary candidate in this respect would be solar energy. In this paper the maximum power point of a PV system is tracked using a fuzzy logic controller. The advantages of a fuzzy logic controller are that it is robust, doesn't require the exact knowledge of the model and is relatively simple to design. Using an FLC (fuzzy logic controller) is considered as an intelligent method of maximum power point tracking.

Keywords – Fuzzy logic controller, Maximum power point tracking, MPPT algorithm, Photovoltaic system

I. INTRODUCTION

Our world is witnessing a lot of energy crisis today and environment pollution is on a rising scale. In order to solve these problems emphasis is being placed on renewable sources of energy. Photovoltaic energy is of great importance in this regard as it is clean and inexhaustible and widely available. As the conventional energy sources are diminishing fast, the solar energy offers a very promising alternative, because it is free, abundant, pollution free and distributed throughout the earth [1].

However there are a lot of challenges in harnessing photovoltaic energy like increasing the efficiency of PV conversion and ensuring the reliability of power electronic converters [2]. Yet another problem with PV systems is that its output varies with temperature and insolation level. These problems are overcome using an MPPT and it increases the overall efficiency of the system.

II. Solar Cell Model

An electrical equivalent model of a solar cell is shown in figure 1. From the circuit it can be seen that the current produced by the solar cell is equal to that produced by the current source, minus that which flows through the diode, minus that which flows through the shunt resistor [3].

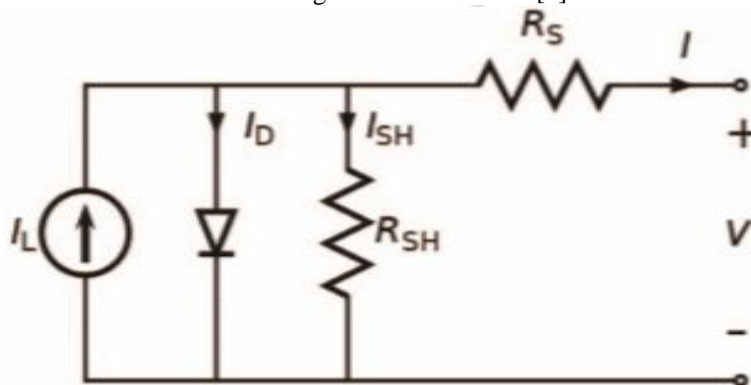


Fig. 1. Electrical equivalent model of solar cell

So we can mathematically express the current produced by the solar cell as,

$$I = I_L - I_D - I_{SH},$$

Where,

I = output current (amperes)

I_L = source current (amperes)

I_D = diode current (amperes)

I_{SH} = shunt current (amperes)

PV modules have unique current v/s voltage (I-V) characteristics. From the P-V and I-V characteristics, as shown in fig. 2, it is clear that the PV systems must be operated at a maximum power point (MPP) of specific current and voltage values so as to increase the PV efficiency [4]. The voltage that corresponds to the module maximum power varies with temperature and insolation variations, so a MPP tracking system is needed to ensure that we stay as close as possible to the maximum power point.

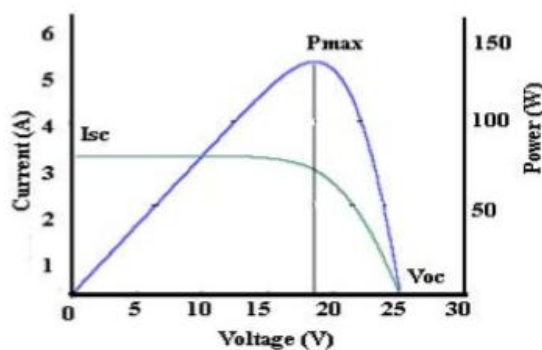


Fig. 2. P, I v/s V curve

III. Mppt (Maximum Power Point Tracking)

For any PV system, the output power can be increased by tracking the MPP (Maximum Power Point) of the PV module by using a controller connected to a dc-dc converter (usually boost converter). However, the MPP changes with insolation level and temperature due to the nonlinear characteristic of PV modules. Each type of PV module has its own specific characteristic. In general, there is a single point on the V-I or V-P curve, called the Maximum Power Point (MPP), at which the entire PV system operates with maximum efficiency and produces its maximum output power. This point can be located with the help of MPPT (Maximum Power Point Trackers) [5]. PV system with MPPT controller has been shown in fig. 3.

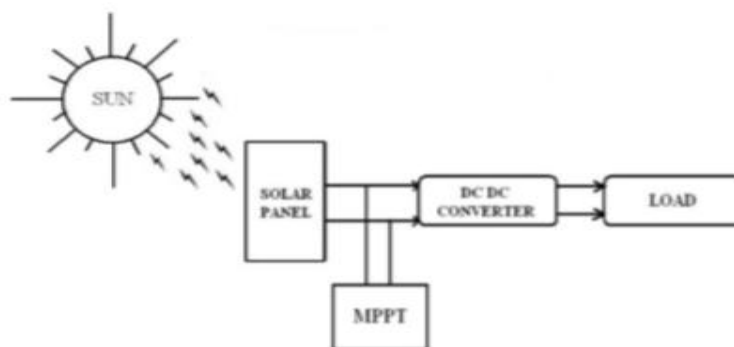


Fig. 3. PV system with MPPT

Maximum Power Point Tracker, frequently referred to as MPPT, is an electronic system that operates the PV modules in a manner that allows the modules to produce all the power they are capable of. MPPT is not a mechanical tracking system that “physically moves” the modules to make them point more directly at the sun. MPPT is a fully electronic system that varies the electrical operating point of the modules so that the modules are able to deliver maximum available power.

IV. Mppt Algorithms

Various algorithms have been proposed for tracking MPP in the past. Commonly used algorithms are Perturb and observe method, Incremental conductance method, Constant voltage method, Constant Current method etc. Perturb & observe method is also known as P&O method. In this method voltage or current of the PV array is modified to reach the MPP. For example the voltage is kept on increasing till the power increases. Constant voltage method is one of the simplest algorithms for MPPT. This method is based on the fact that the ratio of the array’s maximum power voltage, VMPP, to its open-circuit voltage, Voc, is approximately constant. Constant current method is similar to constant voltage method [6].

V. Method For Mppt Tracking

Usually MPPT algorithms are based on the comparison of average values of I_{pv} and V_{pv} . The MPPT scheme here employs a peak current controlled boost dc-dc converter [7]. The output of the MPPT algorithm is the current reference for the peak current controller. By comparing instantaneous values of PV voltage and current at two different sampling instants, the variation of the reference current that would result in an increase of PV output power can be obtained. The basic principle for the operation of the MPPT algorithm can be explained as follows based on Fig. 4. Let us suppose the system is operating on the left side of the MPP and the average value of the PV current rises due to an increase in the reference current. In every switching cycle, I_{pv} increases during switching on and decreases during switching off because of the boost converter. If the sampling time instant in switching cycle $T(k-1)$ is at point A and the sampling time instant in switching cycle $T(k)$ is at point B, the instantaneous current at A, I_A , is less than the instantaneous current at B, I_B . It can be seen from Figure 4(b) that the instantaneous power at A, P_A , is less than the instantaneous power at B, P_B . Therefore, since a positive variation of the instantaneous current resulted in a positive variation of the instantaneous PV power, the reference current I_{ref} should be increased. One can also conclude, from the MPPT algorithm, that the operating point is on the left side of the MPP and that the reference current I_{ref} should be increased to drive the operating point towards the MPP.

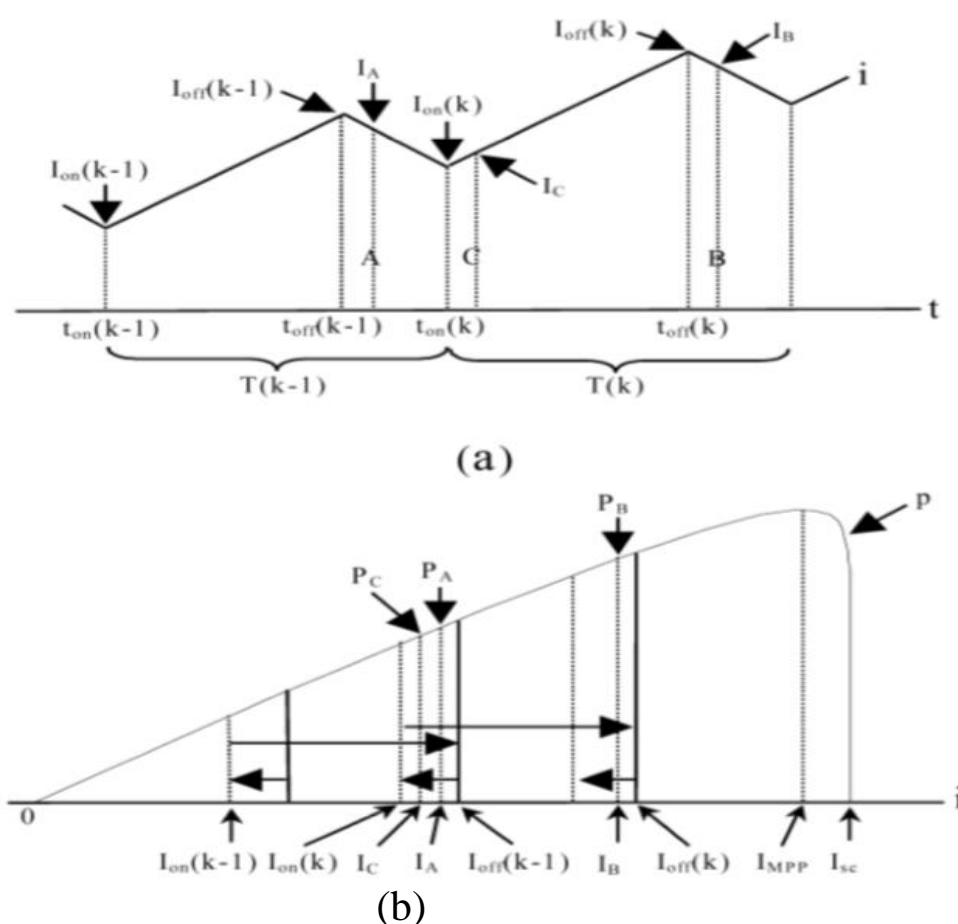


Fig. 4. Operating point on left side of MPP (a) I_{pv} wave form in two switching cycles (b) I_{pv} locus on PI curve.

If the sampling time instant in switching cycle $T(k)$ is at point C instead of point B, the instantaneous samples show that I_C is less than I_A and that P_C is less than P_A . It is clear that with reduction in current value, the power also reduces hence the reference current I_{ref} should be increased.

VI. Fuzzy Logic Controller

Recently fuzzy logic controllers have been introduced in the tracking of the MPP in PV systems. They have the advantage to being robust and relatively simple to design as they do not require the knowledge of the exact model. They do require in the other hand the complete knowledge of the operation of the PV system by the designer. A fuzzy logic controller basically includes – Fuzzification, Rule base, Inference method and Defuzzification method.

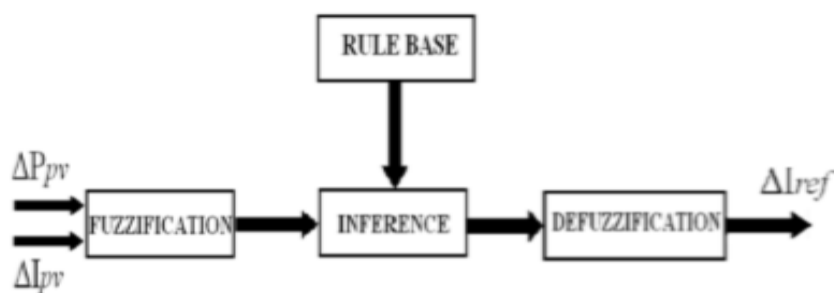


Fig. 5. FLC controller

The inputs to the Fuzzy controller are change in PV array Power (ΔP_{pv}) and change in PV array current (ΔI_{pv}) corresponding to the two sampling time instants. The two inputs are processed by the Fuzzy controller and the output of the Fuzzy controller is the incremental reference current (ΔI_{ref}). This output is given to the Boost converter. Thus during transient conditions the Fuzzy logic controller outputs a larger incremental reference current to speed up the transient response but outputs almost zero incremental reference current near the peak power region to reduce oscillations about the MPP. Fuzzy algorithm tracks the maximum power based on the master-rule: "If the last change in the reference current (ΔI_{ref}) has caused the power to increase keep changing the reference current in the same direction; else if it has caused the power to drop, move it in the opposite direction".

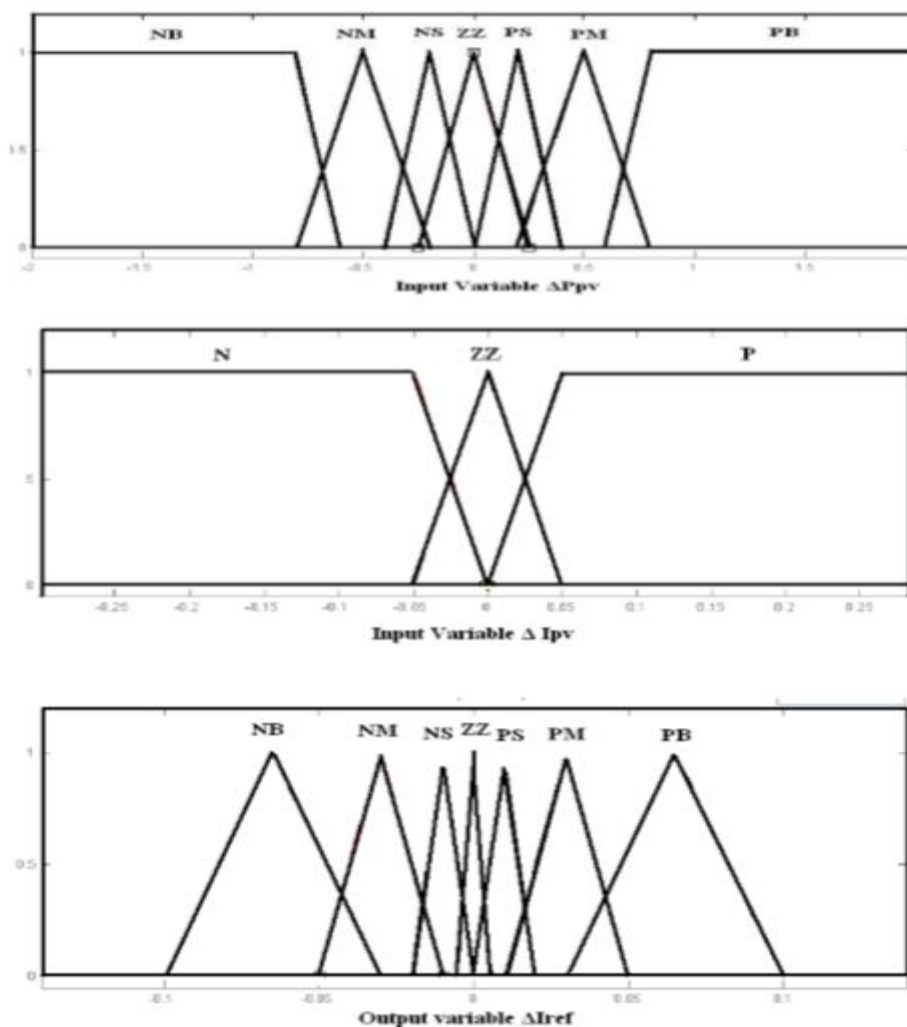


Fig. 6. Input and output membership functions

The universe of discourse for input variable 1 (ΔP_{pv}) is divided into seven Fuzzy sets: PB (Positive Big), PM (Positive Medium), PS (Positive Small), ZZ (Zero), NS (Negative Small), NM (Negative Medium) and NB (Negative Big).
 The universe of discourse for input variable 2 (ΔI_{pv}) is divided into 3 Fuzzy sets: N (Negative), Z (Zero) and P (Positive).
 The universe of discourse for the output variable (ΔI_{ref}) is divided into 7 Fuzzy sets: PB (Positive Big), PM (Positive Medium), PS (Positive Small), ZZ (Zero), NB (Negative Big), NM (Negative Medium) and NS (Negative Small).
 The two inputs are processed by the Fuzzy controller and the output of the Fuzzy controller is the incremental reference current (ΔI_{ref}), which varies in magnitude and polarity depending on which region of the P_{pv} v/s I_{pv} curve, the system is operating on. The output is the reference current to the Boost converter.

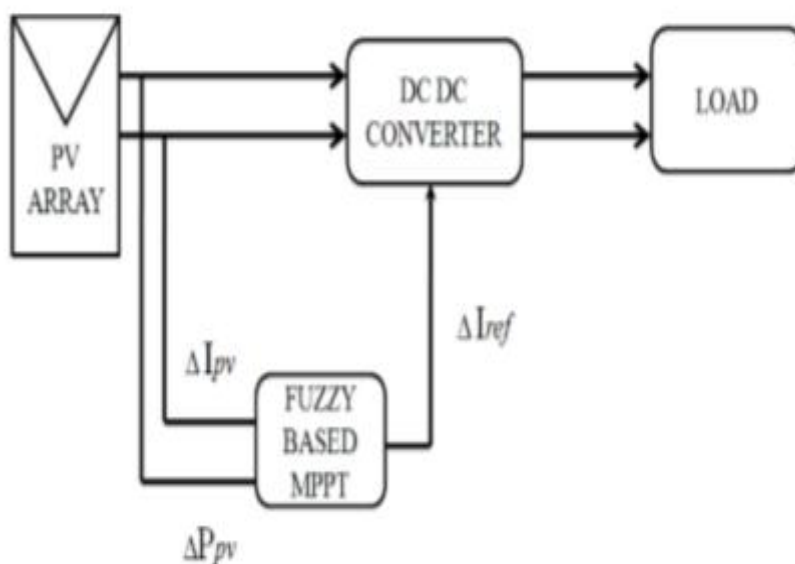


Fig. 7. PV System with MPPT

VII. Simulation & Results

The simulation of the PV system was carried out in MATLAB/Simulink Power Systems environment. The solar array was simulated first and the results for various values of insolation were obtained. The Table I shows the maximum power corresponding to particular insolation

TABLE I
 Maximum power corresponding to particular insolation level.

INSOLATION LEVEL (W/m ²)	MAXIMUM POWER (WATTS)
600	47.47
700	55.88
800	64.32
900	72.79
1000	81.27

The PV model was simulated and the results of simulation for PV system with and without MPPT system have been shown in figure 9, 10 and 11.

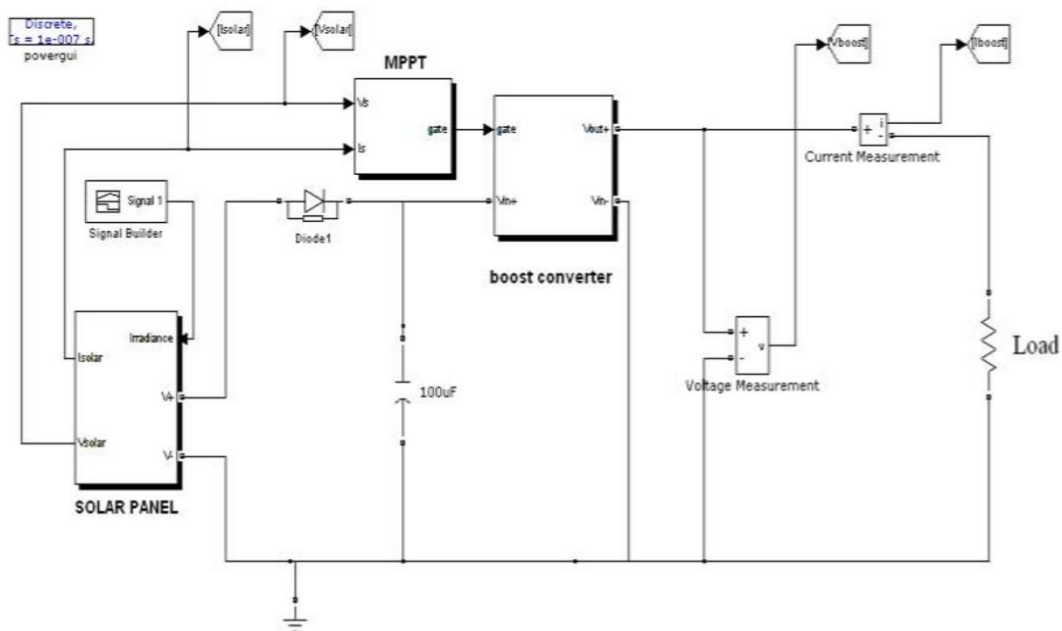


Fig. 8. Matlab model for PV system WITHOUT MPPT CONTROLLER (Insolation level- 600W/m.sq)

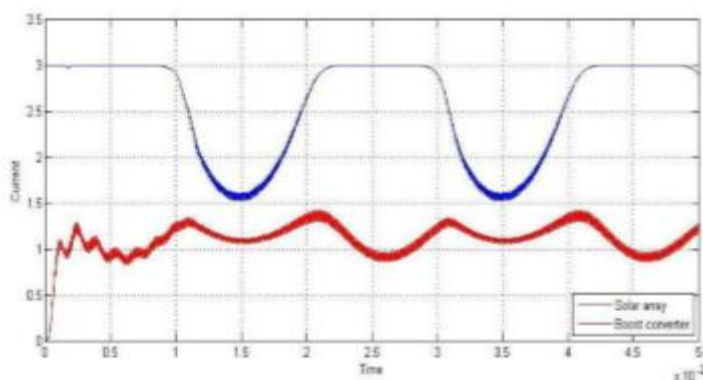


Fig. 9(a). Solar array and boost converter current

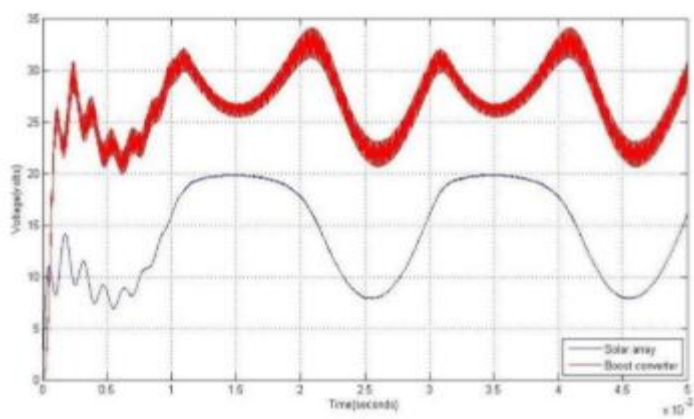


Fig. 9(b). Solar array and boost converter voltage

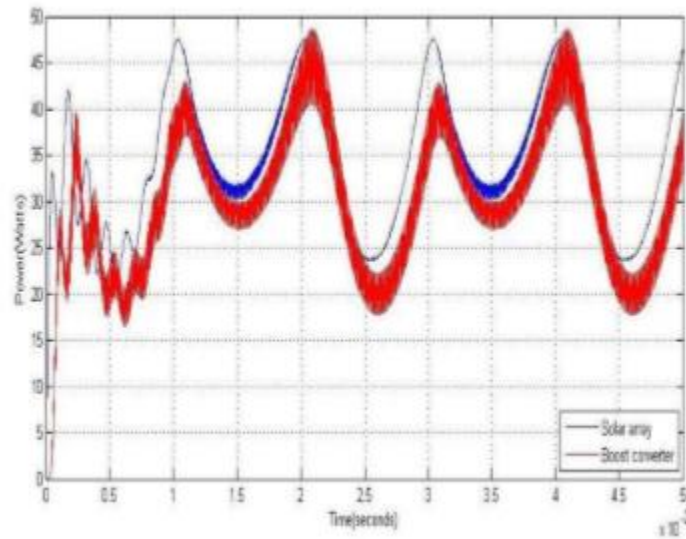


Fig. 9(c). Solar array and boost converter power

WITH MPPT CONTROLLER (Insolation level- 600W/m.sq)

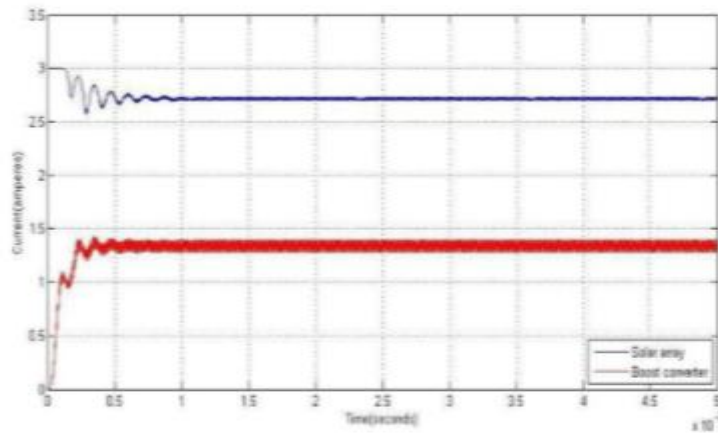


Fig. 10(a). Solar array and boost converter current

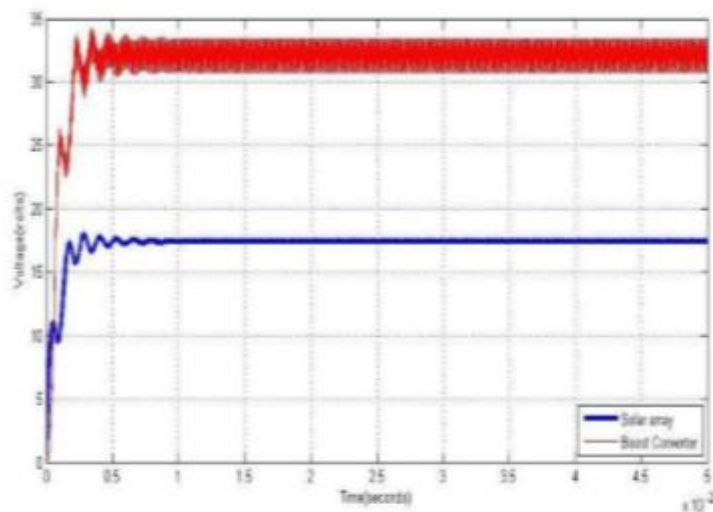


Fig. 10(b). Solar array and boost converter voltage

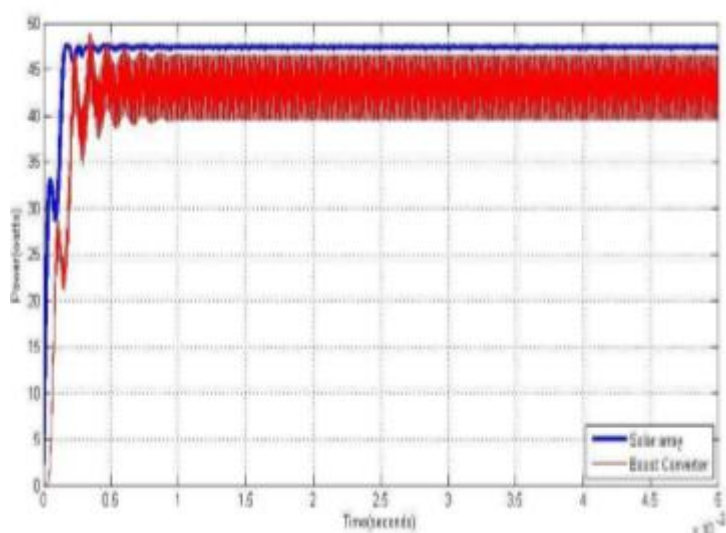


Fig. 10(c). Solar array and boost converter power

Power Output For Varying Insolation Levels

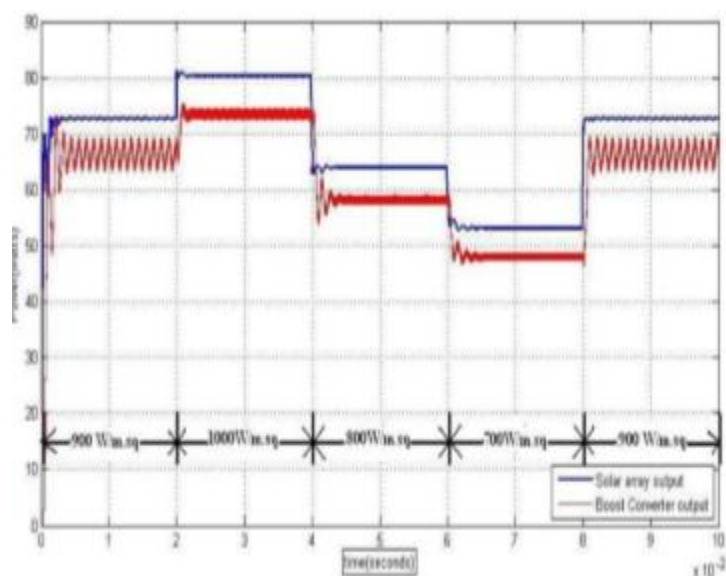


Fig. 11. Solar array and boost converter power

VII. Conclusion

In this paper, a Photovoltaic system with an intelligent Maximum power point tracker (MPPT) has been modeled using Matlab software. The algorithm used for MPPT controller is based on Fuzzy Logic. Fuzzy logic controller is modeled using fuzzy toolbox in MATLAB. The entire PV system was simulated and simulation results are verified. From the results it was clearly found that the PV system becomes more efficient when a MPPT controller is included in the system when compared to a PV system without MPPT controller. Hence it has been proved that the designed controller, with the adequate choice of the membership functions, can make sure that the MPPT will follow the true MPP and thereby the overall efficiency of the PV system can be improved.

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